MyGuide

a project for humanity
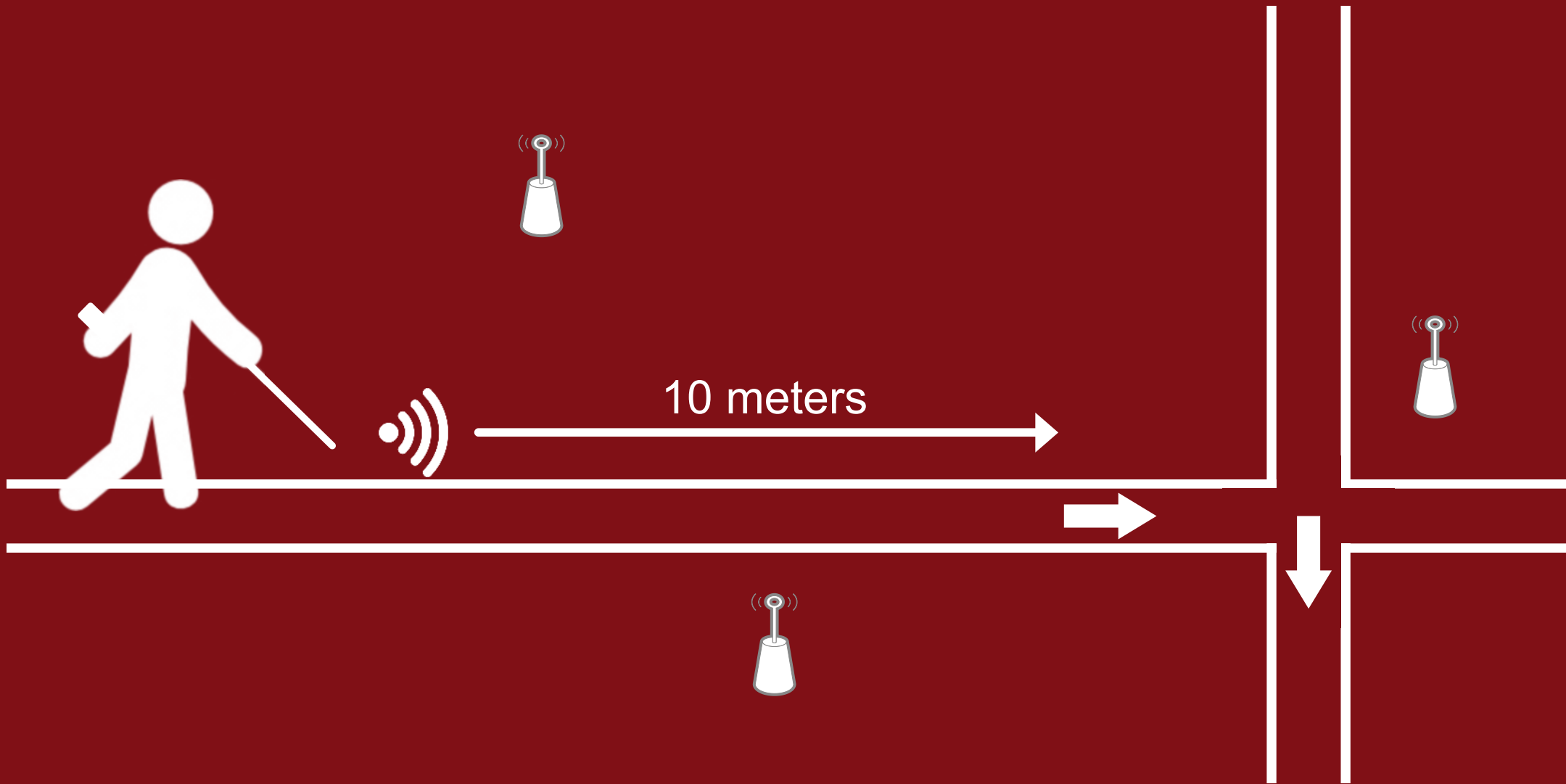
WE ARE 4 STUDENTS FROM 4 COUNTRIES AND 4 DEGREES

OUR VISION IS TO IMPLEMENT
A RELIABLE AND EFFICIENT SYSTEM AIMING
TOWARDS A WHOLE NEW DIMENSION
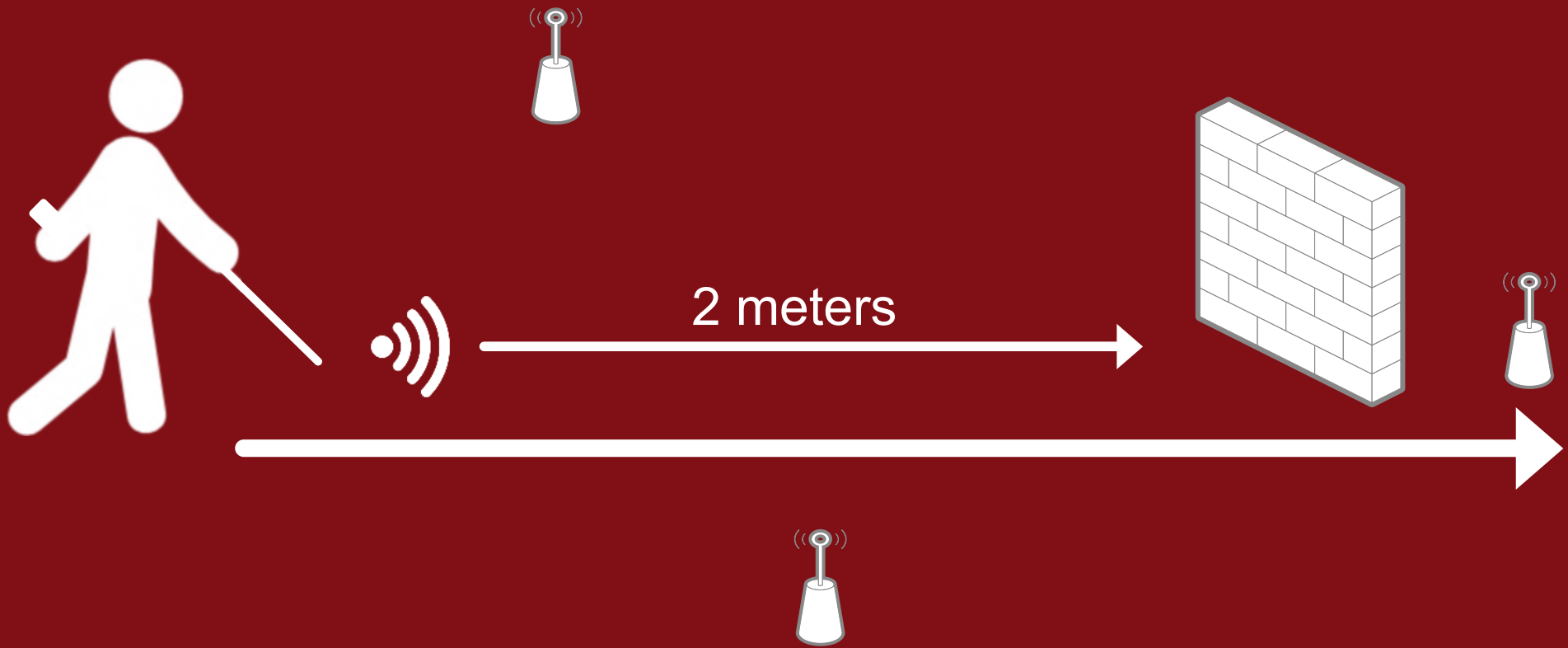OF MOBILITY AND NAVIGATION
FOR POLITECNICO ENVIRONMENT

THE USERS ARE ABLE TO LOCATE THEMSELVES
TO REACH DESIRED DESTINATION
AND ALSO MANEUVER AROUND OBSTACLES
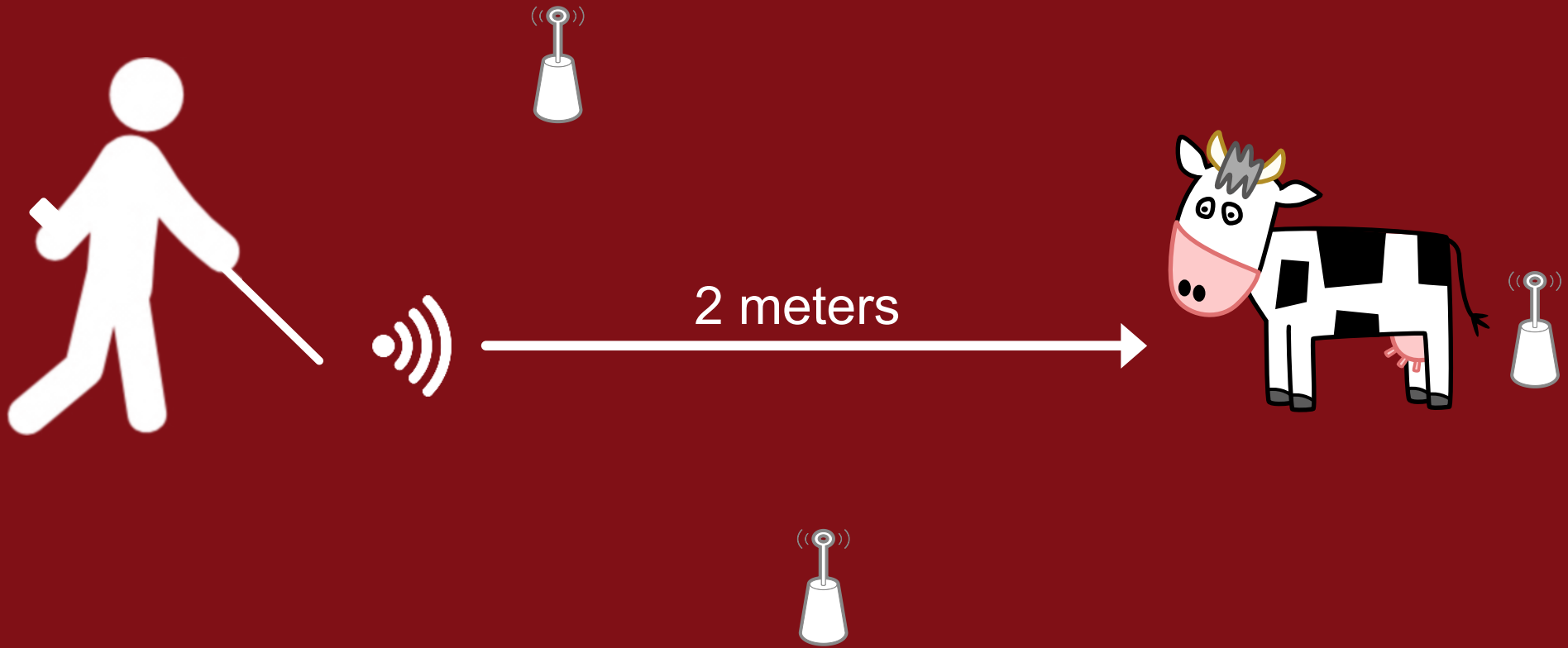INSIDE POLITECNICO

ALL OF THESE
USING MYGUIDE SMART CANE

MYGUIDE IS ABLE TO DETECT OBSTACLES WITH REASONABLE ACCURACY AND ROUTE THE USER THROUGH CROWDED HALLWAYS IN POLITECNICO
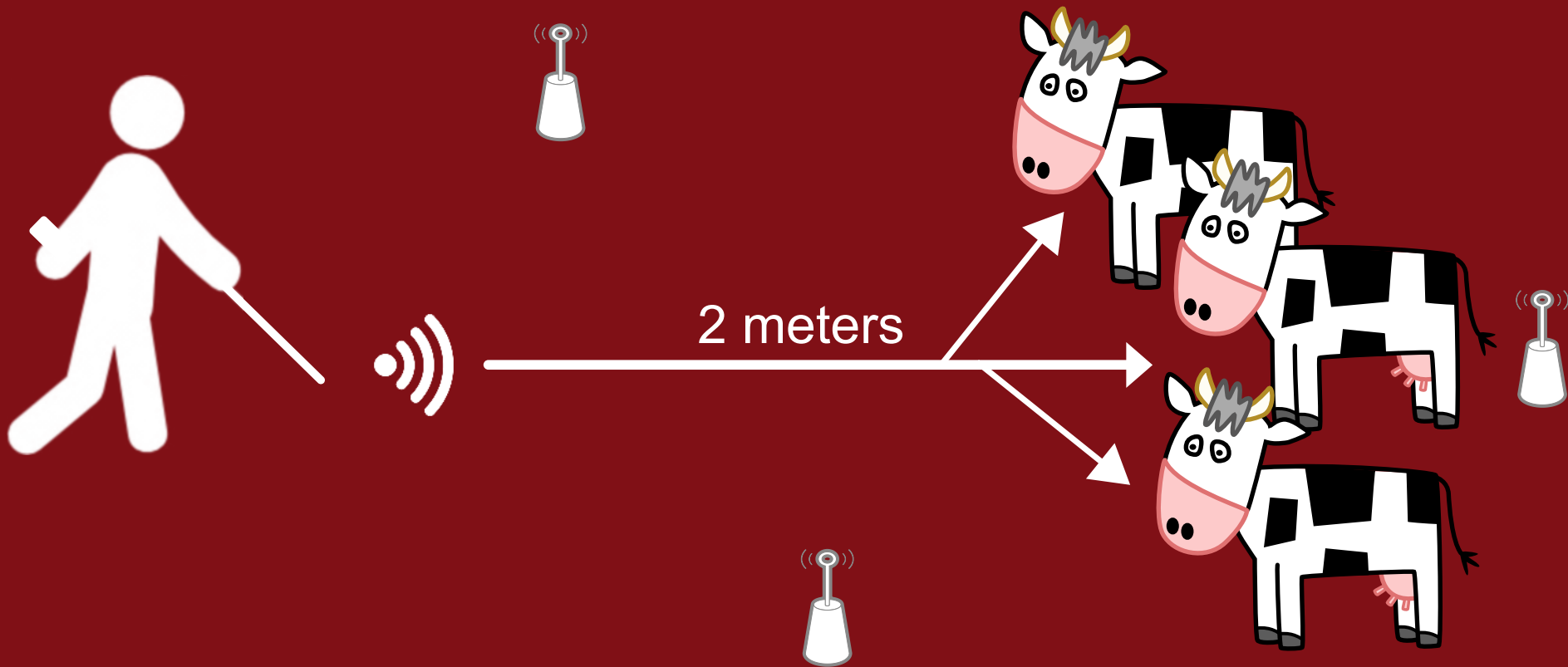
FOR EXAMPLE IF USER NEEDS
TO TURN RIGHT IN 10 METERS,
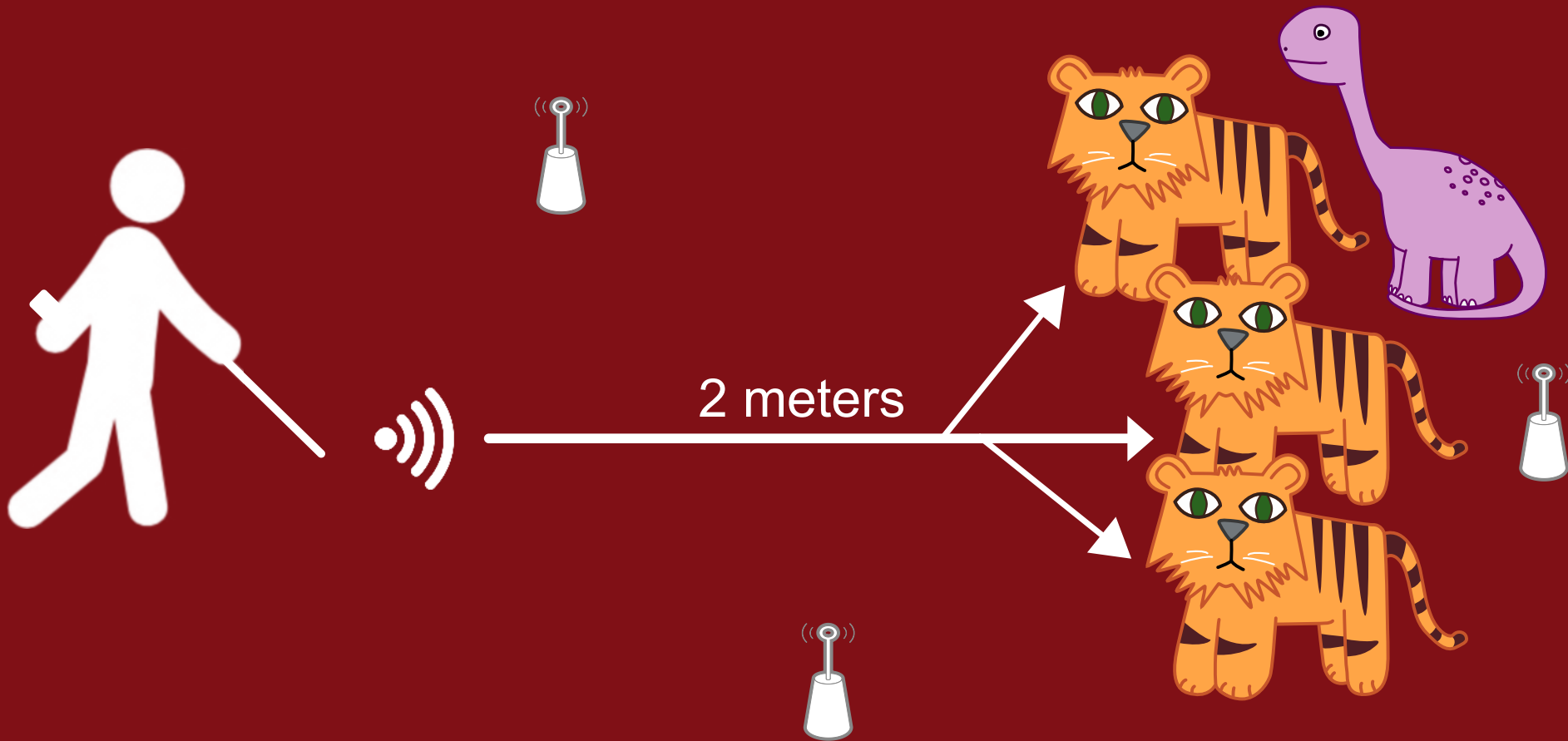MYGUIDE CANE VIBRATES FASTER
AS THE USER APPROACHES THAT LOCATION

10 meters

2 meters

2 meters

2 meters

2 meters

MyGuide

will guide you!

MORE INFO AT:
http://ami-2015.github.io/MyGuide

THANK YOU!